

### ENGINEERED FOR PERFORMANCE

### iADCS400

## Attitude determination and control system

The iADCS400 is a fully autonomous attitude determination and control system aimed at small satellites with a 6U CubeSat form factor or larger

The iADCS400 is joint of development Hyperion Technologies B.V. and Berlin Space Technologies GmbH. It is based on the ST200 tracker. star with RW400 complemented series reaction wheels, MTQ400 series magnetorquers and features an optional precision MEMS gyroscope.

The iADCS400 features an internal fireand-forget controller, which frees up the host processor's workload, providing nadir and target-pointing modes, as well as backup de-tumbling, intentional spin modes and slewing for 6 to 12 U satellites or platforms with similar moments of inertia.

The iADCS400 is delivered with a PC104-compatible footprint, consuming the space of 4 standard CubeSat PCB's, or a total of 0.7 U. This allows the placement of the iADCS400 system anywhere in the CubeSat stack.



#### **HIGHLIGHTS**

- Designed for 6 12 U platforms
- Total momentum storage per axis:
  +/-30 mN.m.s, one reaction wheel per axis
- Maximum torque: 2.5 mN.m
- Three-axis magnetorquer configuration with up to 0.5 A.m<sup>2</sup> of magnetic dipole moment
- Fire-and-forget control
- Standard I<sup>2</sup>C-compatible interface.
  RS422, RS485, U(S)ART and CAN are optional
- Plug-and-play ready design
- Primary components are radiation tolerant up to 45 krad
- Additional radiation shielding built-in
- Interface for external star tracker
- Optional: Built-in OBC/ payload processor
- Low mass: 1150 to 1700 g (dependent on reaction wheels)
- Low power: < 4 W peak</li>
  (< 6W when using optional precision gyro)</li>
- Outer dimensions: 95.4 x 95.9 x 67.3mm





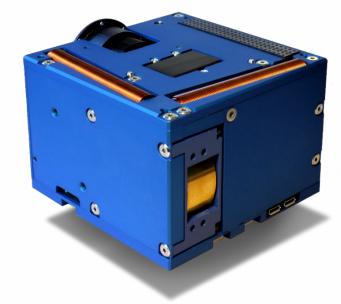
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#### **SPECIFICATIONS**

Performance				
Total momentum storage per axis		+/-15, +/-30, +/-50 <sup>7</sup>		mN.m.s
Maximum torque		2		mN.m
Magnetic moment		X/Y: 0.5 , Z: 0.4		A.m <sup>2</sup>
Attitude determination accuracy		30		arcseconds
Pointing accuracy		<<1		•
Slew rate		> 1.5 <sup>7</sup>		°/s
Radiation tolerance		> 45 <sup>8</sup>		krad (Si)
Operating temperature		- 45 / - 20 to + 40 / + 85 <sup>6</sup>		°C
Dimensions				
		05.4 × 6	) F O v C7 2	
Outer Dimensions		95.4 x 95.9 x 67.3		mm
Mass		1150 / 1300 / 1700 <sup>7</sup>		9
Electrical specifications				
Electrical specifications	Min.	Typ	Max.	
Supply voltage	4.9	Typ. 5.0 <sup>1</sup>	15 <sup>2</sup>	V
Bus logic level voltage	7.5	Referenced to Vsys <sup>3</sup>		V
Power consumption				
Idle	-	-	900 <sup>4</sup> (2400) <sup>4,5</sup>	mW
Nominal	-	2000 <sup>6</sup>	-	mW
Peak	-	-	50000 <sup>4,5,7</sup>	mW

<sup>&</sup>lt;sup>1</sup> When using the 5V system power pins on the standard CubeSat header

<sup>8</sup> Not accounting for Star Trackers and Reaction Wheels used



For pricing, delivery, configuration and ordering information please contact us at **sales@hyperion.space** or call us at **+31(0)15-5160905** 



<sup>&</sup>lt;sup>2</sup>When using the VBAT pin on the standard CubeSat header

<sup>&</sup>lt;sup>3</sup> Vsys can range from 3.3 to 5.1V for I<sup>2</sup>C applications.

<sup>&</sup>lt;sup>4</sup>To be confirmed

<sup>&</sup>lt;sup>5</sup>When using the low drift, high precision gyroscope

<sup>&</sup>lt;sup>6</sup>Can be tailored

<sup>&</sup>lt;sup>7</sup> Depends on reaction wheels used